Probability and Stochastic Processes

Master in Actuarial Sciences

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Continuous time homogeneous Markov chains



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Continuous time homogeneous Markov chains

Definition: continuous time homogeneous Markov chain

Markov process, with countable state space S, in **continuous time**, that has **stationary transition** rates:

• For all $i, j \in S$ exists a probability function $p_{ii}(t)$ such that

 $P(X(s+t) = i | X(s) = i) = p_{ii}(t),$ for all s, t > 0

independent of s.

Remark

For a time homogeneous Markov process $\{X(t)\}_{t\geq 0}$, given its evolution up to any "current" time s, the probabilistic description of its behavior at all future times depends only on the current state X(s) = i, and not on the previous history of the process nor on the time s itself.

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The transition probability matrix

Definition: transition probability matrix at time t

For each $t \ge 0$, we define the matrix $\mathbf{P}(t) = [p_{ij}(t)]_{i,j \in S}$.

Remark

Note that

• For each t, P(t) is a stochastic matrix:

$$p_{ij}(t) \geqslant 0 \hspace{0.1in} orall i, j \in S \hspace{0.1in} ext{and} \hspace{0.1in} \sum_{j \in S} p_{ij}(t) = 1 \hspace{0.1in} orall i \in S$$

• $p_{ij}(0) = 1$, if i = j and $p_{ij}(0) = 0$, if $i \neq j$:

$$p_{ij}(0) = \delta_{ij} \Longleftrightarrow \mathbf{P}(0) = \mathbf{I}$$

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Chapman-Kolmogorov equations

Chapman-Kolmogorov equations

$$p_{ij}(s+t) = \sum_{k \in S} p_{ik}(s) p_{kj}(t), \quad t, s \ge 0, \qquad \forall i, j \in S$$

The transition matrix **P** becomes

$$\left[p_{ij}(t+s)\right]_{i,j\in S} = \mathsf{P}(t+s) = \mathsf{P}(s)\mathsf{P}(t)$$



• We will assume that the probability functions $p_{ij}(t)$ are differentiable.

Definition: transition rates

The transition rate, intensity rate or force of transition, from i to j is defined by

 $q_{ij} = p'_{ij}(0) \quad \forall i,j \in S$

Transition rates

Then, for all $t, h \ge 0$,

$$\begin{split} P(X(t+h) = j | X(t) = i) &= p_{ij}(h) & (\text{homogeneous process}) \\ &= p_{ij}(0) + q_{ij}h + o(h), \text{ as } h \to 0 & (\text{1st order approximation}) \\ &= \delta_{ij} + q_{ij}h + o(h), \text{ as } h \to 0 \end{split}$$

that is, q_{ij} is the (instataneous) transition rate of the process from state i to state j, and

$$p_{ij}(h) = \begin{cases} 1 + q_{ij}h + o(h), & i = j \\ q_{ij}h + o(h), & i \neq j \end{cases}$$

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Remark

Since $\sum_{i \in S} p_{ij}(h) = 1$ e $p_{ii}(h) = 1 + q_{ii}h$, then

$$q_{ii} = -\sum_{j \neq i} q_{ij}$$
 and $\sum_{j \in S} q_{ij} = 0$

Definition: Matrix of transition rates

The matrix

$$\mathbf{Q} = \left[q_{ij}\right]_{i,j\in S}$$

is the transition rate matrix, or intensity matrix, or generator, of the process.

• We assume that:

$$\sum_{j \in S} q_{ij} = 0, \quad orall i$$
 $0 \leqslant q_{ij} < \infty, \quad orall i \neq j$
 $0 \leqslant -q_{ii} < \infty, \quad orall i$

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Remarks

- q_{ij} are not probablities
- It is possible to build the transition probability matrix from the matrix of transition rates
- The matrix of transition rates specifies the probability law of the process



Example

Consider the time continuous Poisson process, such that

$$p_{ij}(t) = rac{e^{-\lambda t} (\lambda t)^{(j-i)}}{(j-i)!}$$

Build the generator matrix of the process.

Example

Consider the Markov process with 2 states and the following transition rates.





The forward differential equations

Theorem: forward differential equations

$$p_{ij}'(t) = \sum_{k \in S} p_{ik}(t) q_{kj}$$

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under the initial conditions $p_{ij}(0) = \delta_{ij}$. In matrix form:

$$\begin{cases} P'(t) = P(t)Q\\ P(0) = I \end{cases}$$

Proof

$$p_{ij}(t+h) = \sum_{k \in S} p_{ik}(t) p_{kj}(h) = \cdots = \sum_{k \in S} p_{ik}(t) [q_{kj}h + o(h)] + p_{ij}(t)$$



The backward differential equations

Theorem: backward differential equations

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$$p_{ij}'(t) = \sum_{k \in S} q_{ik} p_{kj}(t)$$

under the initial conditions $p_{ij}(0) = \delta_{ij}$. In matrix form:

$$\begin{cases} P'(t) = QP(t) \\ P(0) = I \end{cases}$$

Proof

$$p_{ij}(t+h) = \sum_{k \in S} p_{ik}(h) p_{kj}(t) = \cdots = \sum_{k \in S} [q_{ik}h + o(h)] p_{kj}(t) + p_{ij}(t)$$



The forward and backward differential equations





The forward and backward differential equations

Example

General two state process, $S = \{0, 1\}$

$$\mathbf{Q} = \left[egin{array}{cc} -\lambda & \lambda \ \mu & -\mu \end{array}
ight], \qquad \lambda,\mu > 0$$

Find P(t).



The forward and backward differential equations

Example

Time homogeneous health-sickness-death model.





Holding time

$T_0 = \inf\{t : X(t) \neq X(0)\}$

Theorem

The holding time in any state $i \in S$ of a time homogeneous Markov process with transition rate matrix Q is exponential distributed with mean $-\frac{1}{q_{ii}}$. This is to say, that $p_{\overline{ii}}(t) = P(T_0 > t | X(0) = i) = e^{q_{ii}t}$

where

• $p_{ii}(t)$ is the probability that the process remains in state *i* throughout a perid of length *t*.



Notation

- Sometimes we use $q_i = -q_{ii}$, so $p_{ii}(t) = e^{-q_i t}$
- $p_{ii}(t)$ is the probability that the process will remain in state *i* during an interval of range *t*:

$$p_{\overline{ii}}(t) = P(T_0 > t | X(0) = i)$$

• $p_{ii}(t)$ is the probability that, being at state *i*, after a time interval of length *t* we are still back at state *i*:

$$p_{ii}(t) = P(X(t) = i | X(0) = i)$$

• Note that $p_{ii}(t) \neq p_{ii}(t)$



Holding time at state i

$$p_{\overline{i}\overline{i}}(t) = P(T_0 > t | X(0) = i) = e^{q_{\overline{i}\overline{i}}t} = e^{-q_{\overline{i}}t}, \qquad T_i \sim Exp\left(-\frac{1}{q_{\overline{i}\overline{i}}}\right)$$

Proof

$$p_{\overline{ii}}(t+h) = p_{\overline{ii}}(t)p_{\overline{ii}}(h)$$

 $p_{\overline{ii}}(h) = 1 - \sum_{j \neq i} p_{ij}(h)$ and $p_{ij}(h) = hq_{ij} + o(h)$ for $j \neq i$

Hence

$$p_{\overline{i}\overline{i}}(t+h) = p_{\overline{i}\overline{i}}(t) \left[1 + hq_{ii} + o(h)\right]$$

from where

$$p_{\overline{ii}}'(t) = q_{ii}p_{\overline{ii}}(t)$$

So, given that $p_{\overline{ii}}(0) = 1$, we find

$$p_{\overline{i}\overline{i}}(t) = e^{q_{ii}t}$$

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Theorem

The probability that the process goes into state *j* when it leaves state *i* is $\frac{q_{ij}}{-q_{ii}}$.

Proof

$$P(X(t+h) = j|X(t) = i) = q_{ij}h + o(h), \quad i \neq j$$

$$P(X(t+h) \neq i|X(t) = i) = -q_{ii}h + o(h)$$

Hence

$$P(X(t+h) = j|X(t) = i, X(t+h) \neq i) = \frac{P(X(t+h) = j, j \neq i|X(t) = i)}{P(X(t+h) \neq i|X(t) = i)}$$
$$= \frac{q_{ij}h + o(h)}{-q_{ii}h + o(h)} \longrightarrow \frac{q_{ij}}{-q_{ii}}$$

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Definition: m_i

- Let m_i be the expected time for a process to reach state k given that it is currently in state i.
- Then, m_i can be computed using a recursive formula

$$m_i = \frac{1}{-q_{ii}} + \sum_{j \neq k,i} \frac{q_{ij}}{-q_{ii}} m_j$$



Definition: jumping chain

Let

- $\{X(t)\}_{t \ge 0}$ be a CTMC
- Q be the matrix of transition rates (jump intensities) of the process
- W_n be the time of the *n*-th jump:

$$W_0 = 0,$$
 $T_n = W_{n+1} - W_n$ and $P(T_n > t | X(W_n) = i) = e^{q_{ii}t}$

Consider the process

•
$$X_n^* = X(W_n), n \ge 0$$

Then

• $\{X_n^*\}_{n\geq 0}$ is a Markov chain in discrete time, called the **jumping chain** or the embedded Markov chain.

$$\mathbf{P}^* = (p^*_{ij})_{i,j\in S}$$

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Jumping chain of a CTMC

$$P^* = \left(p_{ij}^*\right)_{i,j\in S}$$

such that

$$\begin{cases}
p_{ij}^{*} = \frac{q_{ij}}{-q_{ii}}, & \text{if } j \neq i \\
p_{ii}^{*} = 0 & \text{if } q_{ii} < 0 \\
p_{ij}^{*} = 0, & \text{if } j \neq i \\
p_{ij}^{*} = 1 & \text{if } q_{ii} = 0
\end{cases}$$

Remarks

- Here we are interested in the time instants at which jumps occur
- The transition probability from i to j is the probability that the process jumps from i to j.
- We move from a continuous time (homogeneous) MC to a discrete time (homogeneous) MC

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Reachable state

State j is said to be **reachable** from stacte i for a CTMC if

$$P(X(s) = j | X(0) = i) = p_{ij}(s) > 0$$
, for some $s \ge 0$

Communicating states and classes

- As with discrete-time chains, *i* and *j* are said to **communicate** if state *j* is reachable from state *i*, and state *i* is reachable from state *j*
- It is immediate that *i* and *j* communicate in continuous time if and only if they do so for the embedded discrete-time chain {X_n^{*}}_{n≥0}, *i.e.* they communicate in continuous-time if and only if they do so at transition epochs
- Thus, once again, we can partition the state space into disjoint communication classes

$$S = C_1 \cup C_2 \cup C_3 \cup \cdots$$

- An irreducible chain is a chain for which all states communicate ($S = C_1$, one communication class)
- A CTMC is irreducible if and only if its embedded chain is irreducible
- Q is said to be irreducible if P* is irreducible

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Recurrent state

- State *i* is called **recurrent** if the chain will re-visit state *i* with certainty (with probability 1)
- Otherwise, the state is transient
- State *i* is is recurrent/transient for a CTMC if and only if it is recurrent/transient for the embedded discretre-time chain (although positive recurrent/null recurrent may be different in the two chains)

Periodicity of states

There are no problems of periodicity for the CTMC, although there may exist for $\{X_n^*\}_{n\geq 0}$



Example

Consider the Markov chain in continuous time with the following generator matrix:

O Classify the states.

② Calculate the probability that the process is absorbed at state 5 if it starts from state 1.



Stationary and limiting distribution for a single closed class

Definition

Consider an irreducible CTMC. A probability distribution in S

$$\pi_j \geqslant 0, \quad \forall j \in S \quad \text{and} \quad \sum_{j \in S} \pi_j = 1$$

is stationary if and only if, for all t > 0

 $\pi \mathbf{P}(t) = \pi$

- It is also called **equilibrium distribution** and it gives the long term proportion of time spent in each state.
- If π is stationary, then $\pi_j > 0$, for all j



Stationary and limiting distribution for a single closed class

Theorem

A distribution π is stationary if and only if

 $\pi \mathbf{Q} = \mathbf{0}$

Theorem

Let S be the a single closed class (irreducible chain) of a CTMC. Then, one of the following two is true

1) There is a unique stationary distribution π and

$$\lim_{t\to\infty}p_{ij}(t)=\pi_j,\quad\forall i,j\in S$$

(if S is finite, this case necessarily holds)

2) There is no stationary distribution and

$$\lim_{\to\infty}p_{ij}(t)=0,\quad\forall i,j\in S$$

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Stationary and limiting distribution for a single closed class





Exercise

Vehicles in a certain country are required to be assessed every year for road-worthiness. At one vehicle assessment centre, drivers wait for an average of 15 minutes before the road-worthiness assessment of their vehicle commences. The assessment takes on average 20 minutes to complete. Following the assessment, 80% of vehicles are passed as road-worthy allowing the driver to drive home. A further 15% of vehicles are categorised as "minor fail", these vehicles require on average 30 minutes of repair work before the driver is allowed to drive home. The remaining 5% of vehicles are categorised as "significant fail", these vehicles require on average three hours of repair work before the driver can go home.

A continuous-time Markov model is to be used to model the operation of the vehicle assessment centre, with states W (waiting for the assessment), A (assessment taking place), M (minor repair taking place), S (significant repair taking place) and H (travelling home).

- Explain what assumption must be made about the distribution of the time spent in each state
- Write down the generator matrix of this process.
- Use Kolmogorov's Forward Equations to:
 - Write down differential equations satisfied by $p_{W\!M}(t)$ and by $p_{W\!A}(t)$
 - Verify that $p_{WA}(t) = 4e^{-t/20} 4e^{-t/15}$, for $t \ge 0$, where t is measured in minutes.
 - Derive an expression for $p_{WM}(t)$, for $t \ge 0$.
- Let T_i be the expected length of time (in minutes) until the vehicle can be driven home given that the assessment process is currently in state *i*.
 - Explain why $T_W = 15 + T_A$.
 - Derive corresponding equations for T_A , T_M and T_S .
 - Calculate T_W.

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